

The Effect of Dynamic On-State Resistance to System Losses in GaN-based Hard-Switching Applications

Presented by:



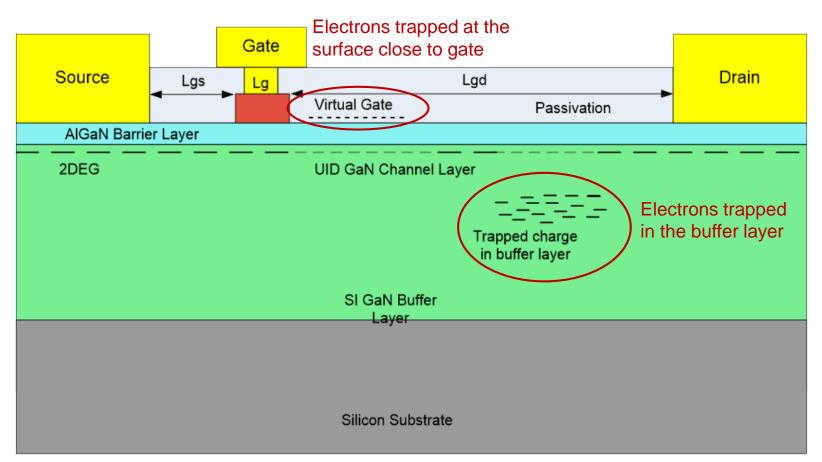
## Introduction

# What is dynamic R<sub>DS(on)</sub>?

- Dynamic R<sub>DS(on)</sub> is due to charge trapping effect of electrons. It results in a decrease of the two-dimensional electron gas (2DEG) density, and therefore, cause the R<sub>DS(on)</sub> to increase. It will cause additional loss for the GaN-based power electronic applications.

#### In this presentation, we will present:

- 1. What is the dynamic R<sub>DS(on)</sub> value?
- 2. How to measure it?
  - Reasonable soak time for pulse test
  - Separation of heating and trapping effects
- 3. What is the percentage of the dynamic R<sub>DS(on)</sub> loss from system-level in a real application?



Lateral GaN HEMT device structure

# Agenda

- Measuring dynamic R<sub>DS(on)</sub>
  - Test setups
  - Soak time variation and its importance
  - Junction temperature variation and conduction loss equation
- Dynamic R<sub>DS(on)</sub> effect on system loss
  - Energy loss distribution in GaN device
  - Comparison to Silicon and Silicon Carbide
- Conclusions

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# Test setup I – pulse test

#### Test setup I:

Double pulse test (DPT) with soak time and T<sub>i</sub> control

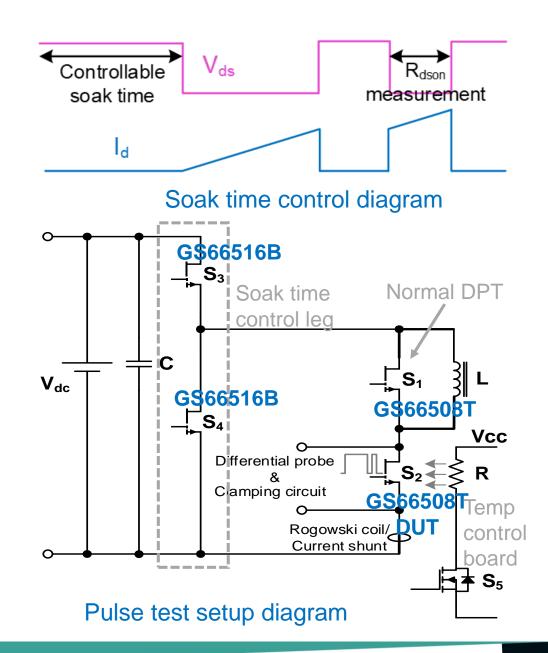
#### Device under test (DUT): GS66508T GaN HEMT

#### **Measurement equipment:**

- Off-state  $V_{DS}$  measurement  $\rightarrow$  Differential probe
- On-state  $V_{DS(on)}$  measurement  $\rightarrow$  Clamping circuit
- I<sub>D</sub> measurement → Rogowski coil/Current shunt
- T<sub>i</sub> measurement → Thermal camera

#### **Control variables:**

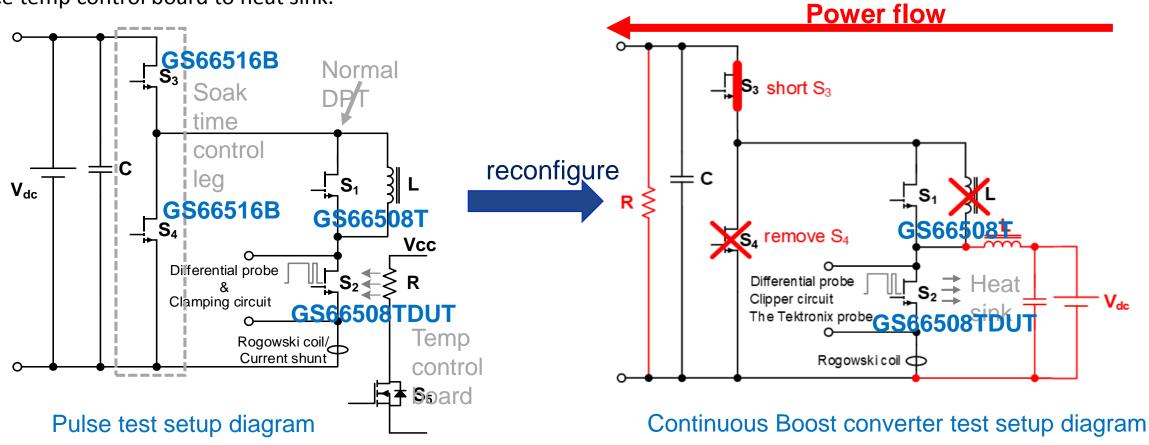
- Soak time Control → Extra half-bridge S<sub>3</sub>/S<sub>4</sub>
- $T_i$  Control  $\rightarrow$  Heating resistor/NTC thermistor
- V<sub>DS</sub>, I<sub>D</sub>, and on-time → DPT
- DSP controls all four gates (S<sub>1</sub>-S<sub>4</sub>)



# Test setup II – continuous test

#### **Test setup II: Continuous Boost converter setup**

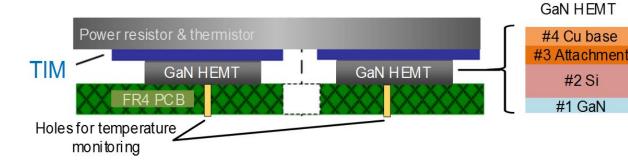
- DPT test setup can be reconfigured to a Boost converter setup for continuous test with the following changes,
  - 1. Remove/short soak time control leg;
  - 2. Change power source, load and inductor position;
  - 3. Replace temp control board to heat sink.



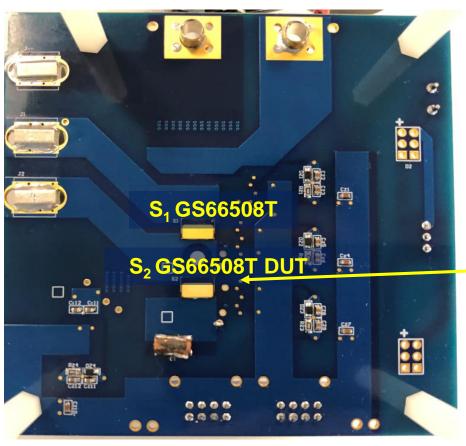
# Pulse test setup – bottom view

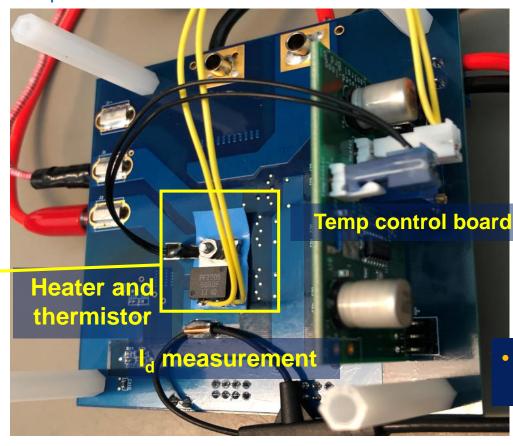
- GS66508T-based half-bridge on the bottom side
- The heater and thermistor are installed upon DUT switch S<sub>2</sub>
- Temperature is also monitored by thermal camera

Bottom view with and without temperature control board



Monitored temperature thru thermal holes on the back side

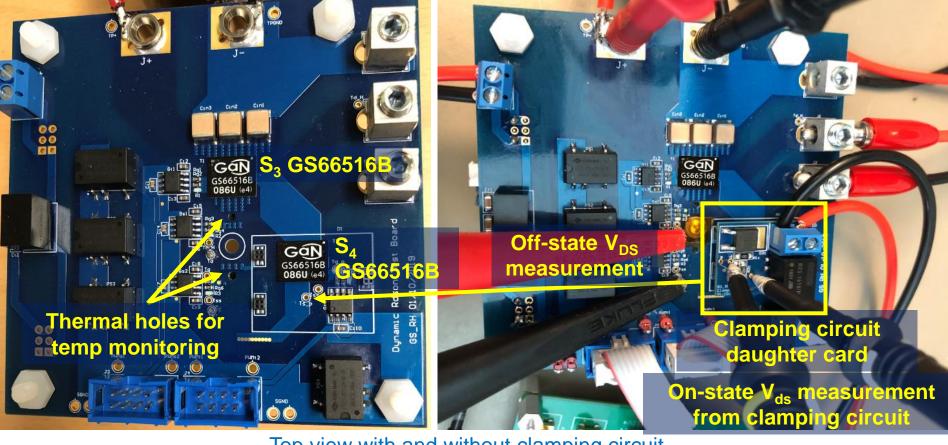


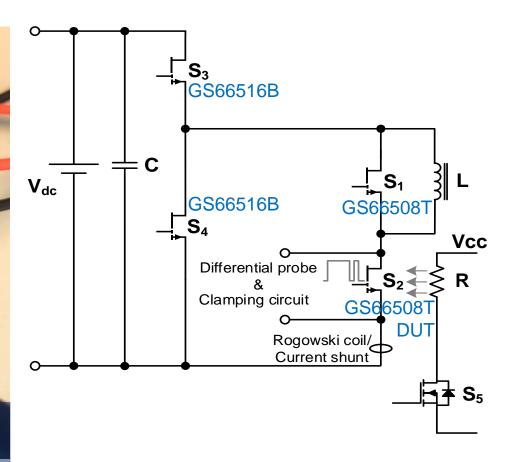


Good T<sub>j</sub> monitoring is important to separate heating and trapping effects

# Pulse test setup – top view

- GS66516B-based half-bridge on the top side
- The clamping circuit board is installed upon switch S<sub>4</sub> and close to DUT S<sub>2</sub>



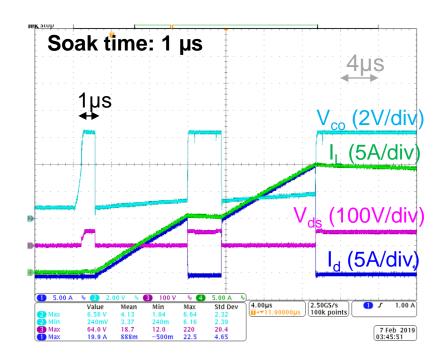


Top view with and without clamping circuit

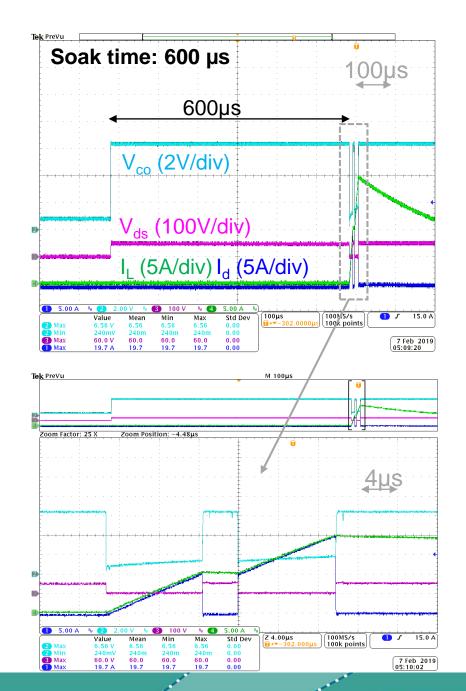
Pulse test setup diagram

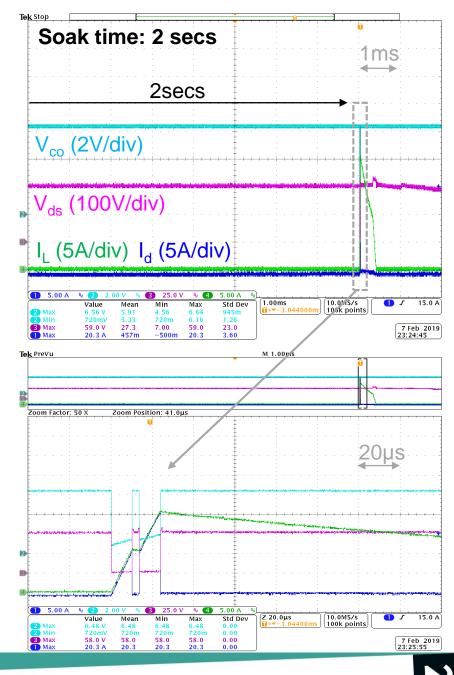
# Soak time variation

# **DPT** examples with different soak times



Controllable soak time is achieved by controlling the halfbridge S<sub>3</sub>/S<sub>4</sub>



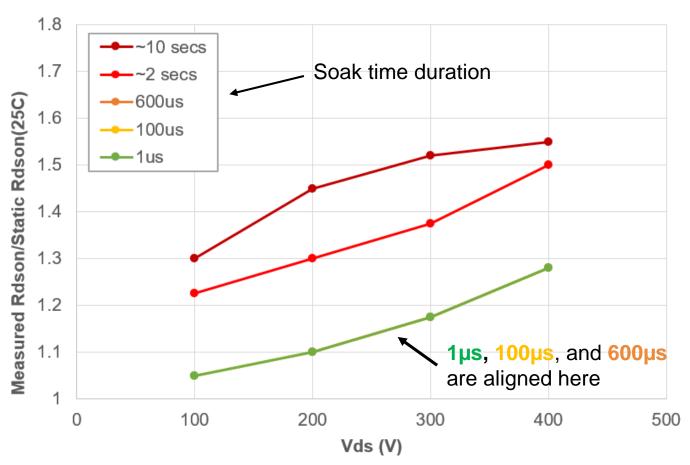


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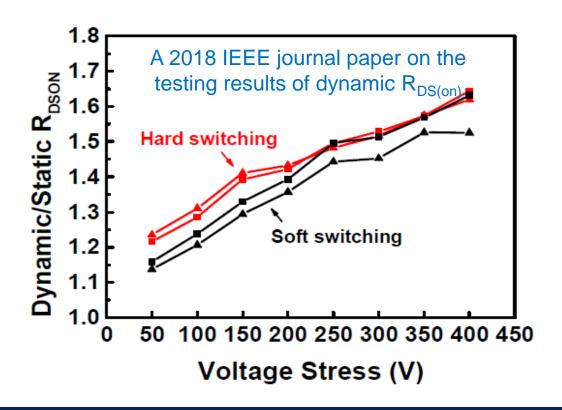


# Dynamic R<sub>DS(on)</sub> results with soak time control

# Summary on soak time vs. V<sub>ds</sub>



A Typical example of academic technical papers (without soak time control):



- Soak time impacts dynamic R<sub>DS(on)</sub> results. Improper soak time give erroneous results
- For accurate power loss evaluation, evaluate dynamic  $R_{DS(on)}$  at the soak time of your power system, 1 to 100  $\mu$ s

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# $R_{DS(on)}$ heating effect, $k_{Ti}$ factor

#### Heating effect on the GS66508T DUT (device is characterized before all tests):

 $R_{DS(on)}$ @25°C = 43.28 mohm

 $R_{DS(on)}$ @75°C = 64.5 mohm

R<sub>DS(on)</sub>**@75°C/**R<sub>DS(on)</sub>@25°C=**1.49** 

The normalized increased R<sub>DS(on)</sub> due to 75°C heating is 0.49

 $(k_{Ti}=0.49)$ 

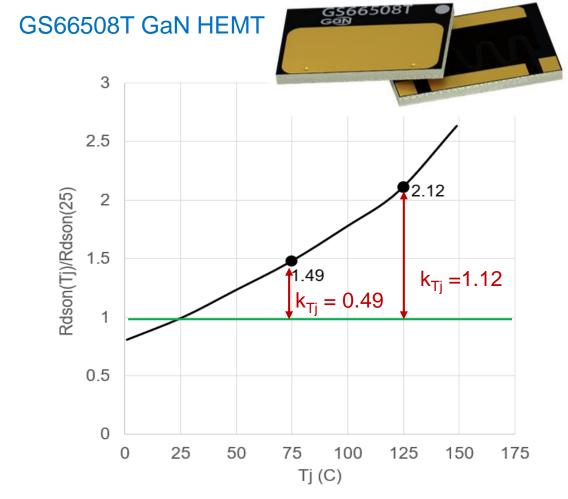
 $R_{DS(on)}@125^{\circ}C = 91.7 \text{ mohm}$ 

R<sub>DS(on)</sub>@**125°C/**R<sub>DS(on)</sub>@25°C=**2.12** 

The normalized increased R<sub>DS(on)</sub> due to 125°C heating is 1.12

 $(k_{Ti}=1.12)$ 

**k**<sub>Ti</sub> is the normalized increased R<sub>DS(on)</sub> from heating effect



DUT R<sub>DS(on)</sub> vs. T<sub>i</sub> characterization

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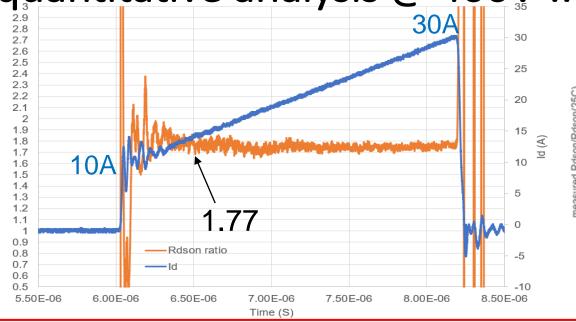


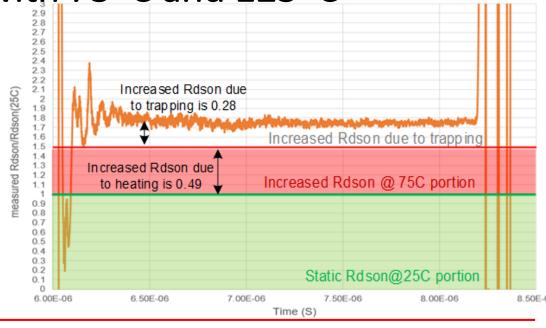
R<sub>DS(on)</sub> decoupling quantitative analysis @ 400\ with 75°C and 125°C

Measured  $R_{DS(on)}$  @ 75°C, 400V,  $I_D$  ramp up from 10A to 30A,  $T_{soak}$ =1 $\mu$ s

 $k_{Tj} = 0.49$ 

 $k_{dr} = 0.28$ 



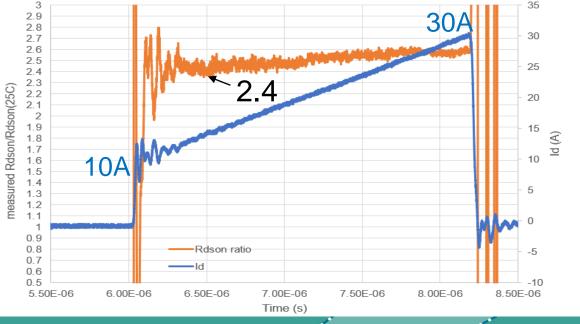


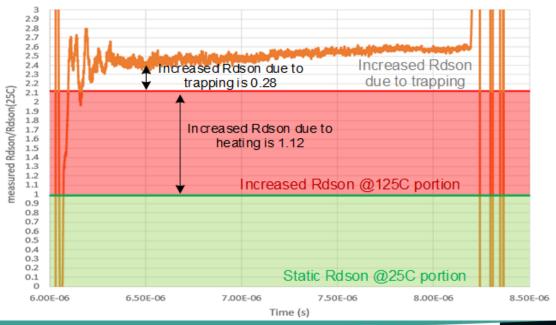
Measured  $R_{DS(on)}$  @ 125°C, 400V,  $I_D$  ramp up from 10A to 30A,  $T_{soak}$ =1 $\mu$ s

 $k_{Ti} = 1.12$ 

 $k_{dr} = 0.28$ 

 Good T<sub>j</sub> monitoring is important to separate heating and trapping effects





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# PECFRONICS

# Conduction loss calculation with *k* factors

Different types of conduction loss calculation considering dynamic R<sub>DS(on)</sub>

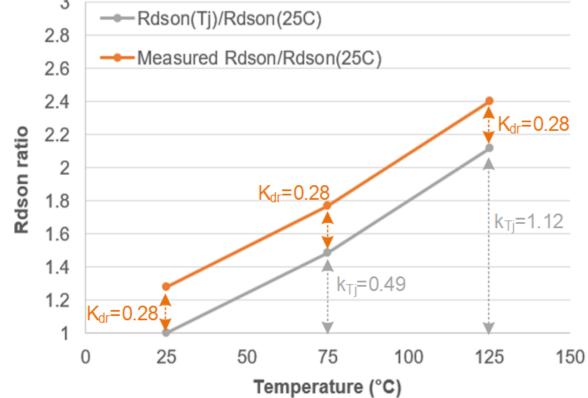
#### Definition of *k* factors:

- $k_{Tj}$  is the normalized increased  $R_{DS(on)}$  portion from heating effect. Normalized to static  $R_{DS(on)(25C)}$ .
- $k_{dr}$  is the normalized increased  $R_{DS(on)}$  portion from trapping effect. Normalized to static  $R_{DS(on)(25C)}$ .

#### Loss iteration with *k* factors:

- Good thing about using the factor  $k_{dr}$  is it is temperature independent.
- 1. An simpler loss calculation (still only one curve fittings with  $T_i$ :  $k_{Ti}$ ).
- 2. Easy for loss iteration calculation.

Solution (on)		
	$I^{2}R_{DS(on)(25C)}^{*}(1+k_{Tj})^{*}(1+k_{dr})$	$I^2R_{DS(on)(25C)}^*(1+k_{Tj}+k_{dr})$
	Previous misunderstanding on loss calculation	Proposed loss calculation
Accuracy?		
	3 Rdson(Ti)/Rdson(25C)	



Summary on R<sub>DS(on)</sub> ratios vs. junction temperature T<sub>j</sub>

As  $T_j \nearrow \longrightarrow R_{DS(on)(Tj)}$  or  $k_{Tj} \nearrow \longrightarrow k_{dr}$  constant with  $T_i$ 

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# Conduction loss calculation made simple and accurate

**Example:** conduction loss calculation considering dynamic R<sub>DS(on)</sub>

If  $R_{DS(on)(25C)}$ =43.27 mohm,  $I_{RMS}$ =10 A, and  $T_i$ =125 °C

#### Different types of conduction loss calculation considering dynamic R<sub>DS(on)</sub>

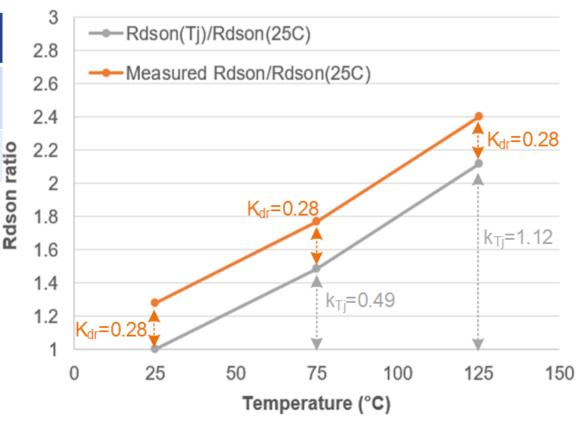
	$I^{2}R_{DS(on)(25C)}^{*}(1+k_{Tj})^{*}(1+k_{dr})$	$I^2R_{DS(on)(25C)}^*(1+k_{Tj}+k_{dr})$
	4.327x(1+1.12)x(1+0.28)=11.74 W	4.327x(1+1.12+0.28)=10.38 W
Accuracy?		

That's 11.74-10.38=1.36 W difference, even without considering self-heating;

For engineers who are more familiar with energy loss, this is like 13.6 μJ\*100 kHz=1.36 W;

If the thermal resistance is about 8 °C/W, that's 10 °C difference.

- $k_{dr}$  is the simple easy way to calculate dynamic  $R_{DS(on)}$
- Use power loss =  $I^2R_{DS(on)(25C)}^*(1+k_{T_i}+k_{dr})$  for simple and accurate results



Summary on R<sub>DS(on)</sub> ratios vs. junction temperature T<sub>i</sub>

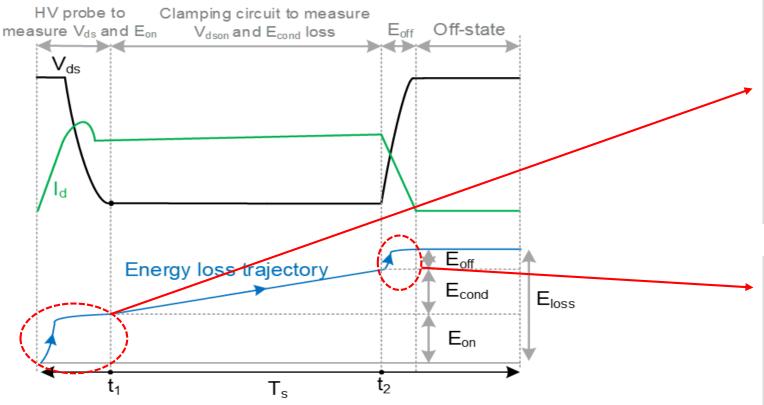
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# Energy loss distribution in GaN device

By knowing V<sub>DS</sub>, I<sub>D</sub>, conduction time, and T<sub>i</sub>, the energy loss is accumulated and the final overall loss can be obtained.

The energy loss trajectory also presents the overall loss breakdown.



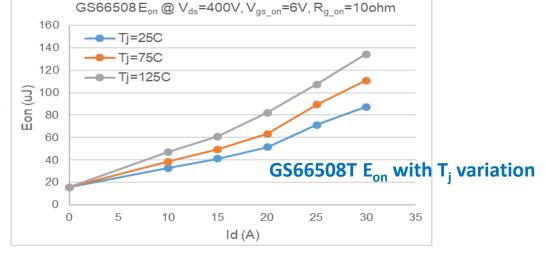
A hard-switching cycle of GaN HEMT and its energy loss trajectory

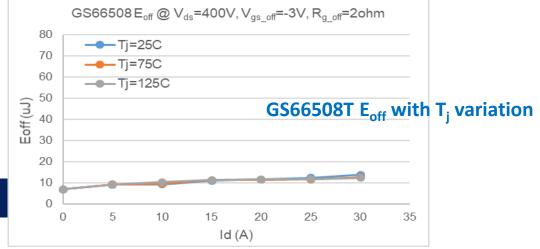
The impact of dynamic R<sub>DS(on)</sub> should be compared to the overall loss in a switching cycle

Please refer to GS technical papers below for more details on switching loss E<sub>on</sub>/E<sub>off</sub>:

1. R. Hou, J. Lu, and D. Chen, "Parasitic capacitance  $E_{aoss}$  loss mechanism, calculation, and measurement in hard-switching for GaN HEMTs," in *Proc. 2018 IEEE APEC*, San Antonio, TX, Mar. 2018.

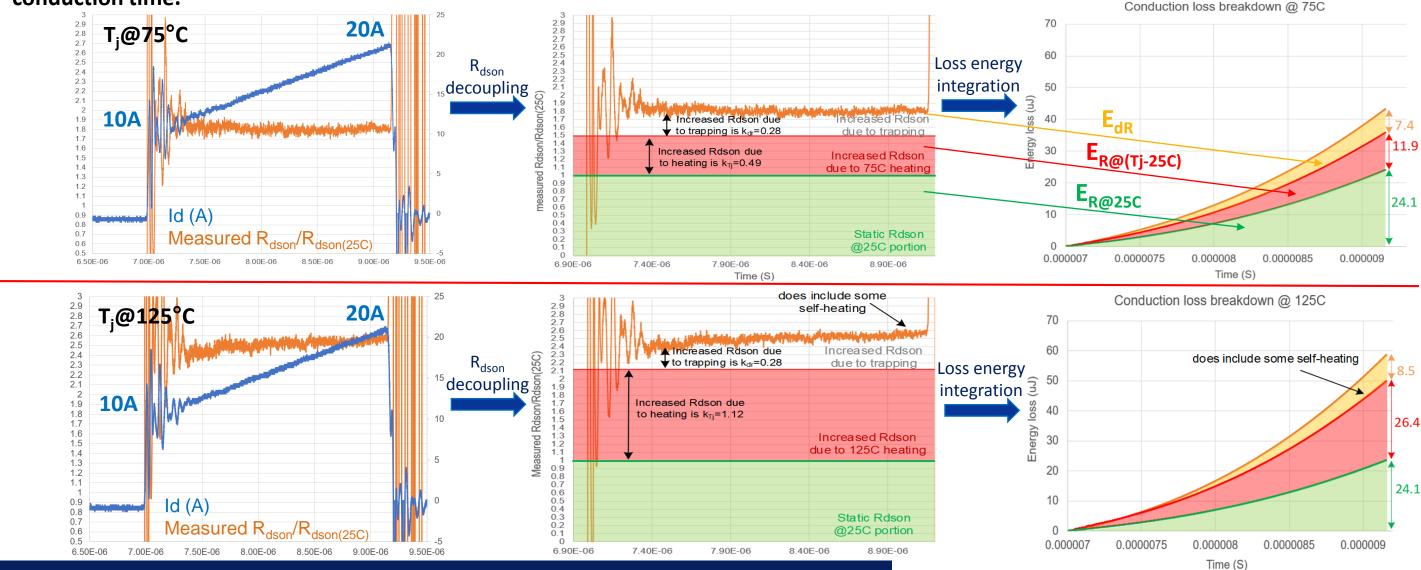
2. R. Hou, J. Xu, and D. Chen, "Multivariable turn-on/turn-off switching loss scaling approach for high-voltage GaN HEMTs in a hard-switching half-bridge configuration," in *Proc. 2017 IEEE WiPDA*, Albuquerque, NM, Oct. 2017.





# Examples - conduction loss distribution @ 75°C and 125°C

• Two 400 V examples: T<sub>i</sub> of 75 °C & 125 °C. For both, device V<sub>DS</sub> voltage is 400 V, current starts at 10 A then ramps up to 20 A with a 2.2 μS conduction time.



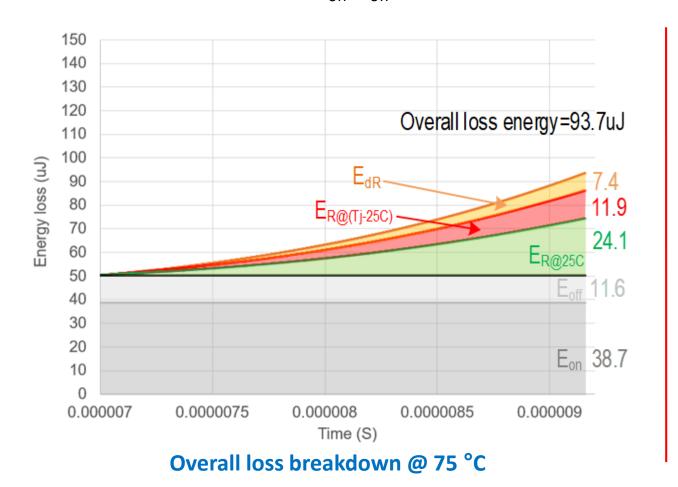
With increasing T<sub>i</sub>, trapping effect loss becomes less significant compared to heating effect loss

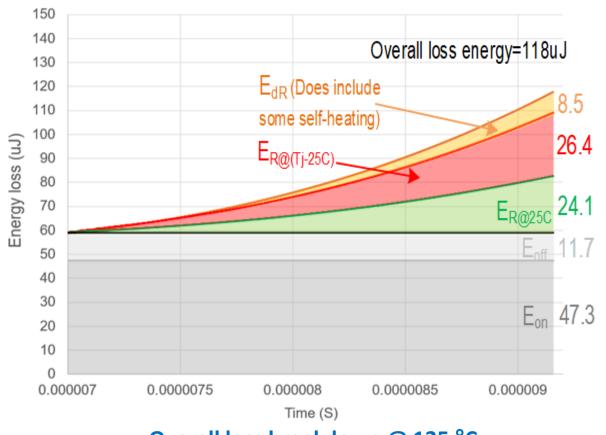
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# Examples – overall loss distribution based on pulse test

- In conduction loss, with  $T_i$  increasing, the  $R_{DS(on)}$  loss from trapping effect becomes less significant than heating effect.
- By adding the switching loss  $E_{on}/E_{off}$ , the overall loss for one switching cycle can be obtained.



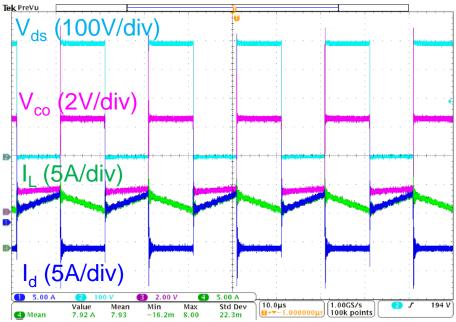


Overall loss breakdown @ 125 °C

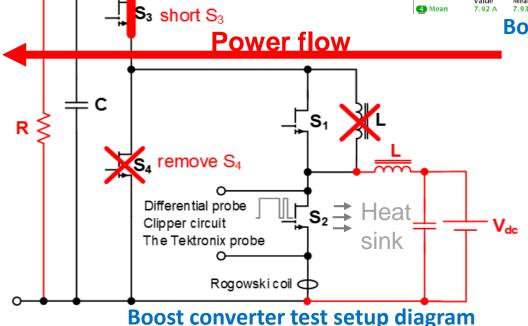
Compared to E<sub>on</sub>, the dynamic R<sub>DS(on)</sub> loss has a very small effect on the system efficiency

# Loss distribution for GaN HEMT based on continuous Boost test

 The test setup is reconfigured to a Boost converter for continuous running.

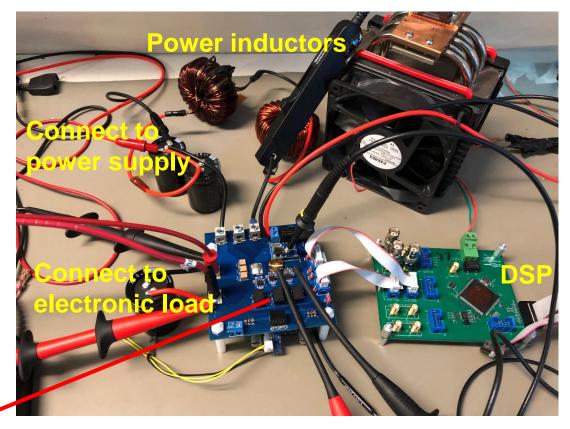


**Boost converter waveforms** 





**Heatsink installation** 



**Boost converter test setup** 

- Temperature control board is removed and replaced by a heatsink attached on the GS66508T device on the PCB bottom side.
- T<sub>i</sub> is still monitored through thermal hole.

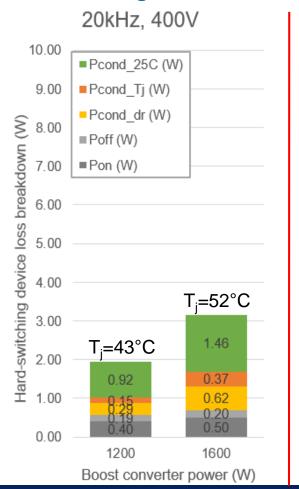
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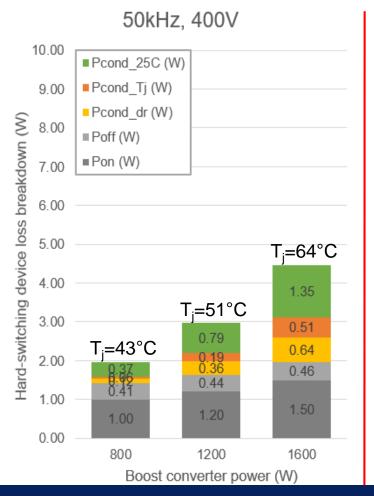


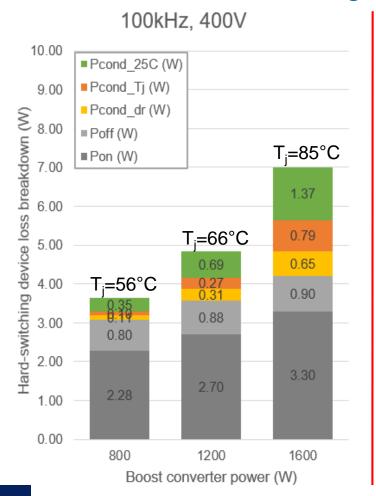
## Loss distribution for GaN HEMT based on continuous Boost test

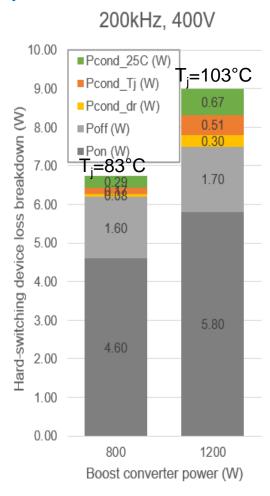
- Converter continuous tests are performed with different load currents and switching frequencies
- $V_{in}$ =200 V,  $V_{out}$ =400 V,  $R_{th ia}$ =8.7 °C/W,  $T_{amb}$ =25 °C

Hard-switching device loss breakdown in a GaN-based Boost converter under different loads and switching frequencies







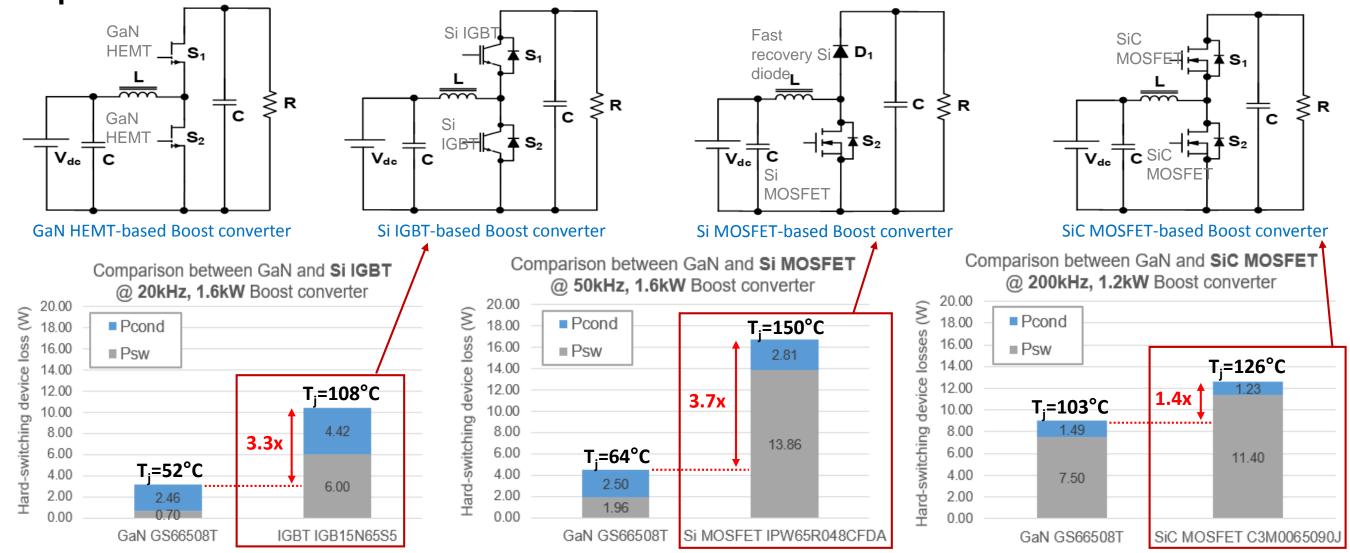


Power loss due to dynamic R<sub>DS(on)</sub> is a small portion of total system loss

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Comparison to Silicon and Silicon Carbide



- Overall, GaN has much lower losses compared to Silicon and SiC, 1.4x to 3.7x lower
- GaN has significant advantages over other technologies on switching loss E<sub>op</sub>/E<sub>off</sub>

# Conclusions

# • Dynamic R<sub>DS(on)</sub>

- Measurement:
  - Good T<sub>i</sub> monitoring is important to separate heating and trapping effects;
  - Continuous mode test provides the most accurate results;
  - Soak time control (typically 1 to 100 μs) is needed.
- Loss calculation: use  $I^2R_{DS(on)(25C)}^*(1+k_{Ti}+k_{dr})$  for simple and accurate results
- The trapping effect (dynamic  $R_{DS(on)}$ ) is **significantly less** than the heating (temperature) effect

#### System Power loss

- Power loss due to dynamic R<sub>DS(on)</sub> is a small portion of total system power loss
- Total system power loss: GaN outperforms other technologies by a wide margin

# Thank you for your attention!

Have a good day.

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