# celduc® relais

DC SWITCHING





19 juni 2019 1931 Congrescentrum 's-Hertogenbosch POWERONICS





## SUMMARY

Celduc Relais introduction

DC switching technologies:

- Bipolar
- Mosfet
- IGBT (SCI)
- IGBT (SDI)

U & I ranges by Celduc Relais

New technologies

- Mosfet SIC
- Mosfet GAN







## SUMMARY

Necessary protections of DC relays

- Energy
- Passive Over Voltage components
- Active Over Voltage protection

Energy

Passive components

- TVS
- VDR

Active Over Voltage protection

Short circuit protection







# SUMMARY

#### Applications

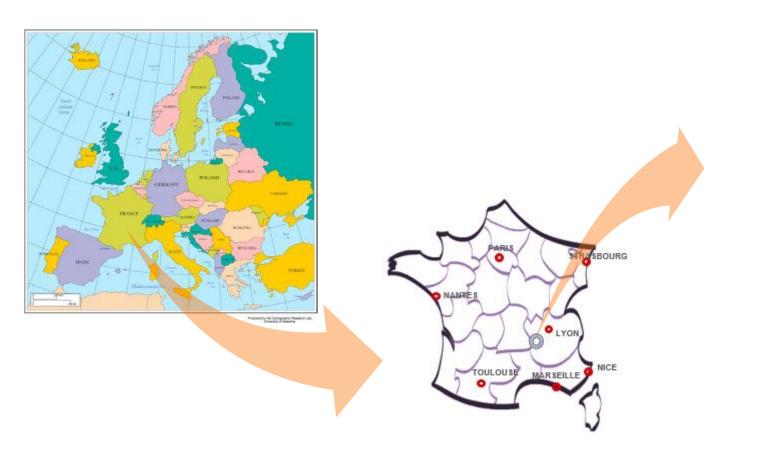
- Heating (tramways) Active clamp
- Reversing motors



# **COMPANY OVERVIEW**







- Close to St-Etienne
- 60 km from Lyon
- 500 km from Paris



• Turnover 2018 : 26,6M€

Employees: 150



# **PRODUCTS**







- Solid-State Relays (SSR)
- Power Controllers
- 73% of the Turnover



- Magnetic sensors for level, position, speed, safety
- 24% of the Turnover



- Reed switches and relays
- 3% of the Turnover

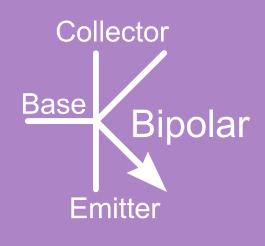






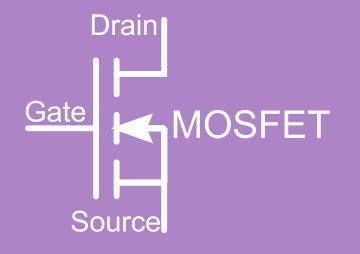
## DC SWITCHING TECHNOLOGY

# **Bipolar Transistor**



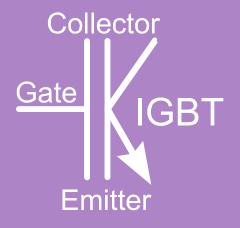
#### **MOSFET**

( Metal Oxide Semiconductor Field Effect Transistor )



#### **IGBT**

(Insulated Gate Bipolar Transistor)



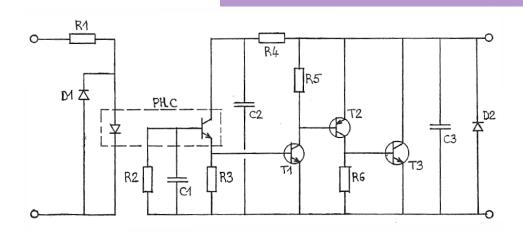








# DC SWITCHING TECHNOLOGIES ⇒ BIPOLAR TRANSISTOR



It is a current amplifier.
In bipolar DC SSR (e.g. SCC, SKD...), the control current is amplified through PHC, T1, T2 to T3.

Advantage: The SSR can be controlled by a very small input current

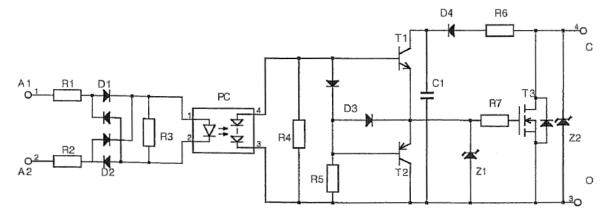
**Disadvantages**: The voltage drop is quite high at low load voltage even at low load current.

Difficult to reach high voltage because of the number of amplifying stages required (complexity)





## 



In Mosfet DC relays (e.g. SCM,SOM,SPD,SKLD...) the input control current generates Gate voltage through Photovoltaic PC

Advantage: The relay has a very low voltage drop for low load voltage

**Disadvantages**: The control current is quite high due to the low efficiency of the photovoltaic generator.

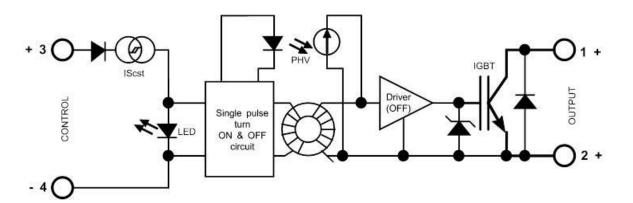
The relay has a high voltage drop for high load voltage







# DC SWITCHING TECHNOLOGIES ⇒ IGBT (SCI)



In SCI DC relays the input control current generates Gate voltage through the pulse transformer for a good switch ON and the photovoltaic PHV maintains the supply of gate voltage.

Advantage: Low voltage drop for high load voltage

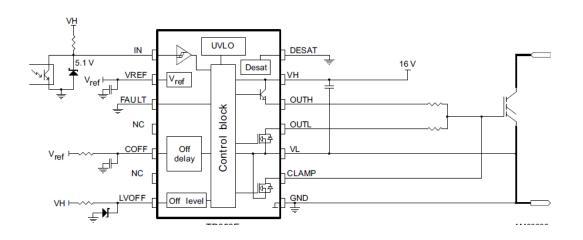
**Disadvantage**: The control current is quite high due to the low efficiency of the photovoltaic generator.







## DC SWITCHING TECHNOLOGIES ⇒ IGBT (SDI)



In DC relays (e.g. SDI) the input control current generates Gate voltage through a negative (turn OFF) and positive (turn ON) supply

Advantages: Low voltage drop for high load voltage

Low control current

Integrated Protection (UVLO, Desaturation detection...)

Better turn OFF with negative gate voltage

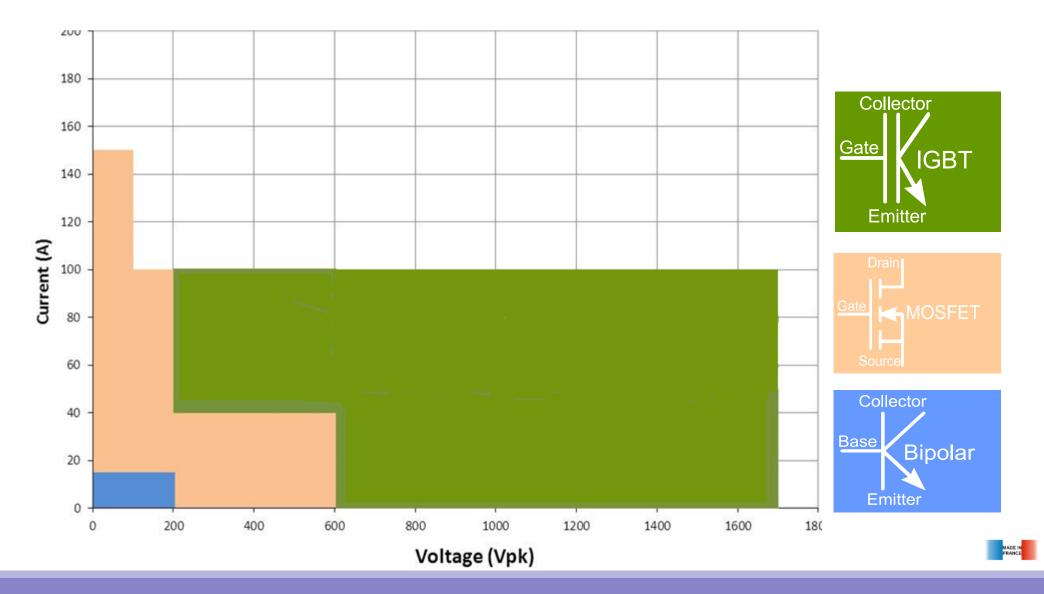
**Disadvantage**: Requires an auxiliary supply



#### **Present celduc solutions**







#### **BENCHMARKING**





## New technologies like SIC-MOSFETS and **GAN-MOSFETS**

- Lower RdsON
- High switching performance, higher voltage
- Higher junction T°C

BUT STILL TOO EXPENSIVE TODAY FOR USE IN SSR







• OVER-VOLTAGES FROM MAINS, WIRES, LOADS...

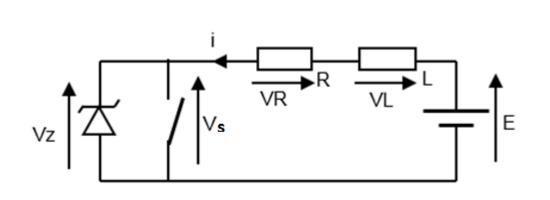
SHORT CIRCUIT



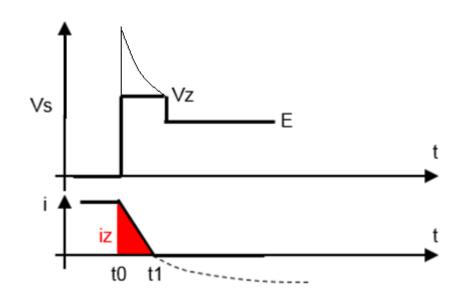




ENERGY AT SWITCH OFF



Opening the switch



Over-voltage and energy







## **Formulas**

Ip Initial current = E/R

E<sub>L</sub> Initial energy in  $L = \frac{1}{2} L Ip^2$ 

Pz instant power = Vz Ip

Ez energy in Zener = (Vz.Tau/R).[E+(Vz-E).ln(1-E/Vz)]

With Tau = L/R











## Difficult to stop the current!

 $E=0.5 \times L \times I^{2}$ 

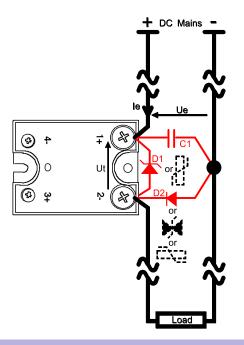
« E » is the energy stored in the wires or in inductive loads.

This energy must be dissipated when switching OFF.

L is the circuit inductance and « I » is the load current.

Current at turn OFF is the <u>LOAD</u> current!!!

A voltage protection is mandatory!







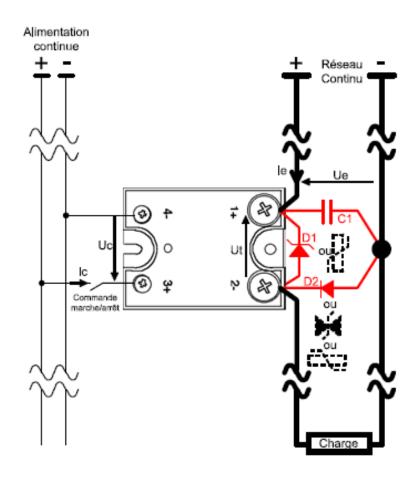


 PROTECTION WITH PASSIVE COMPONENTS

 PROTECTION BY ACTIVE CLAMP







Why C1, D1 and D2?

C1 to compensate the line inductance from the mains (dv/dt)

D1 protects the relay against overvoltages, mains and load

D2 is the free-wheel diode. It will allow magnetic energy stored in load and lines to flow, finally dissipated in heat (Joule's law)







TVS: Transient Voltage Suppressor

Can be unidirectional or bidirectional

Fast response but limited energy

VDR: Voltage Dependent Resistor

**Bidirectional** 

More energy but ageing









#### Differences between varistor and Transil

	Varistor	Transil
Topology	Bidirectional	Uni or Bidirectional
Leakagecurrent	< 5 μA	< 1 µA
8/20μs Clamping factors (= Vcl / Vbr)	2.00	1.5
ESD ruggedness	> 30 kV	> 30 kV
ESD clamping voltage	See Figure 6	See Figure 6
Ageing	Yes, see Figure 7	Yes, see Figure 7









Figure 7. Aging effect on both varistor and Transil characteristics

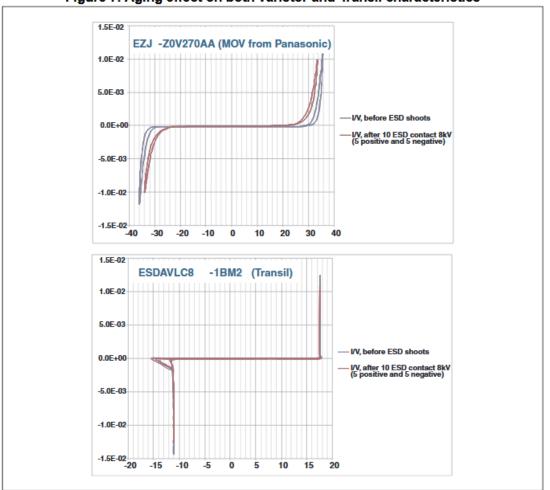
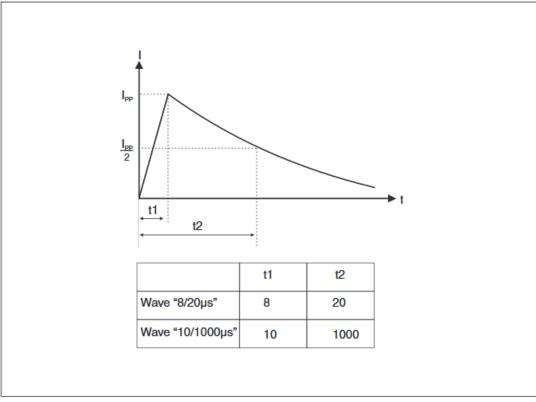


Figure 7 shows the impact of repetitive ESD IEC 61000-4-2 level 4 contact discharge surges. After 10 surges, the I/V characteristics of the varistor changed while the Transil one presents no change.

Figure 2. Standard exponential pulse



This type of pulse corresponds to most of the standards used for the protection device.

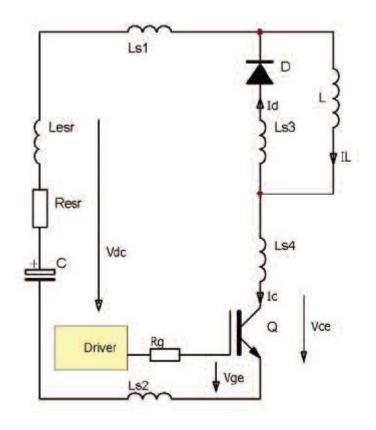


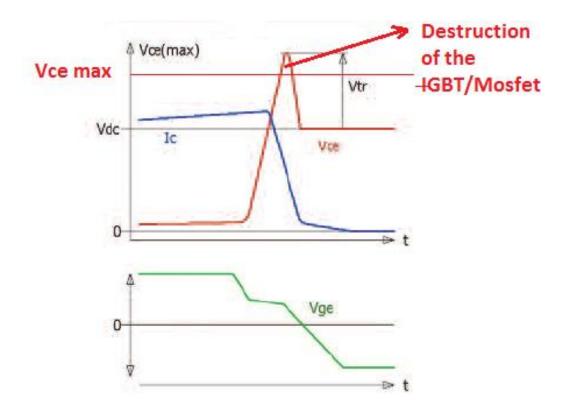






### **ACTIVE CLAMP**



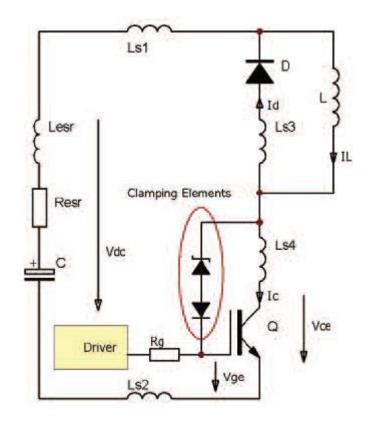


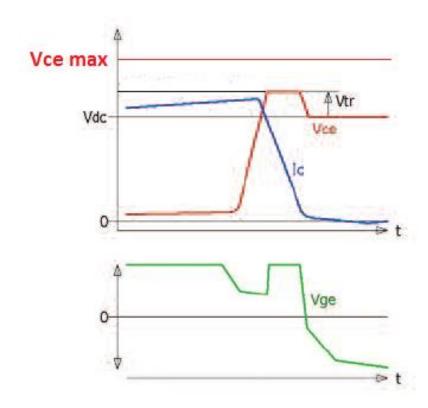






### **ACTIVE CLAMP**







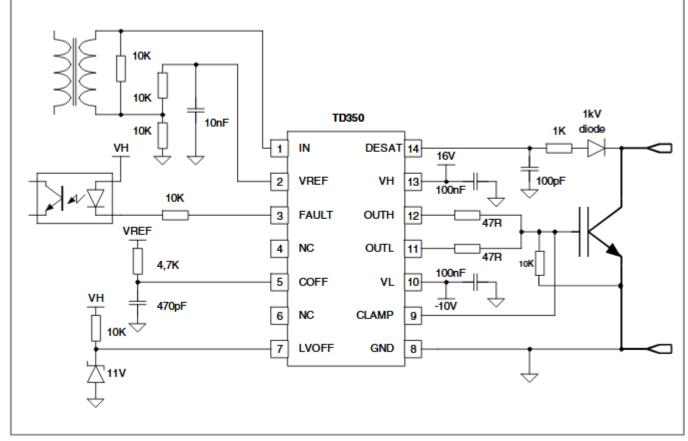




#### **SHORT CIRCUIT**

Driver chips for IGBT control

Figure 1. TD350 application example showing all the features



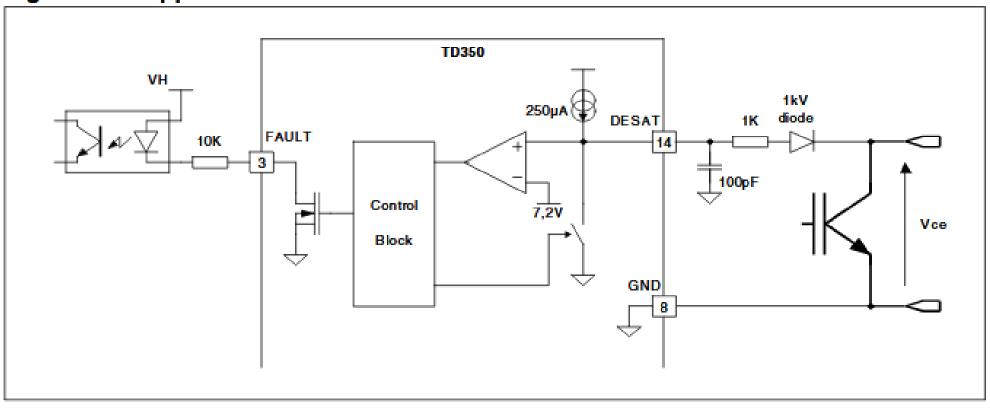






#### **SHORT CIRCUIT**

Figure 14. Application schematic for DESAT feature



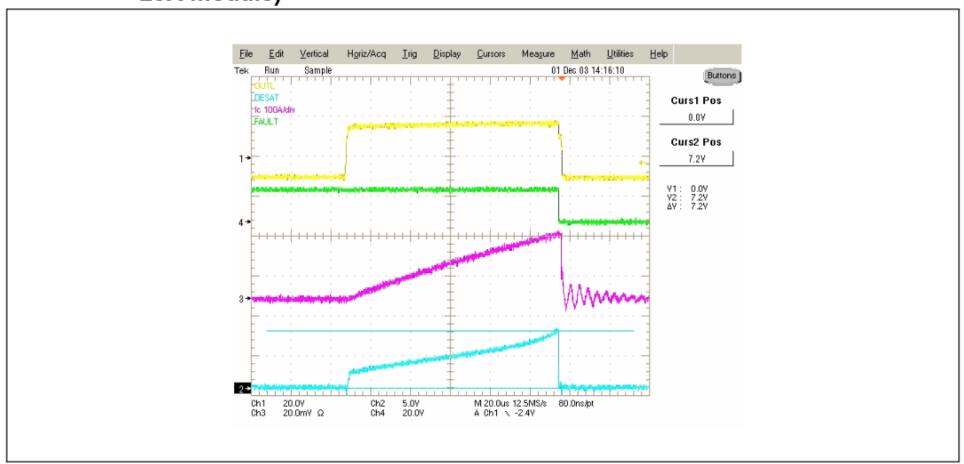


#### **SHORT CIRCUIT**





Figure 15. The collector current ramp-up to 150A triggers the DESAT feature (test on 25A module)









## **APPLICATIONS**

## HEATING (TRAMWAY) WITH ACTIVE CLAMP





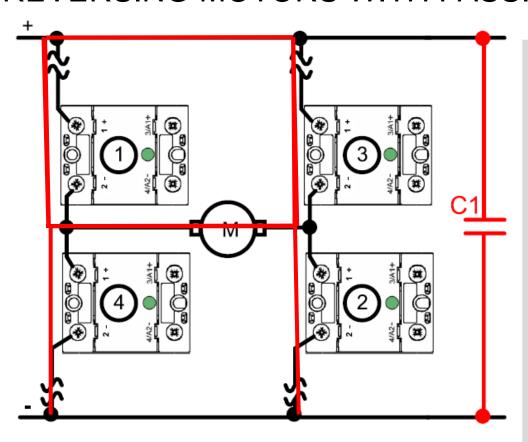






#### **APPLICATIONS**

#### REVERSING MOTORS WITH PASSIVE CLAMP



#### Motor direction 1:

Control of « 1 » Control of « 2 »

#### PWM:

« 1 » permanently controlled« 2 » controlled with PWM signal or vice-versa

#### Change of direction:

Control OFF of « 2 » Wait 1 second mini (Flywheel) Control OFF of « 1 » Proceed with Motor direction 2

#### Motor direction 2:

Control of « 3 » Control of « 4 »

#### PWM:

« 3 » permanently controlled« 4 » controlled with PWM signal or vice-versa

#### Change of direction:

Control OFF of « 4 » Wait 1 second mini (Flywheel) Control OFF of « 3 » Proceed with Motor direction 1



### THANKS FOR YOUR ATTENTION

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