

Inverters & Motor Drive Analysis

CN Rood/Tektronix

Sven De Coster





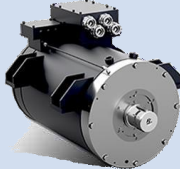


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ENERGY STORAGE



Types of Motors

Classified by design technology

BLDC Motor (Brushless DC)	Induction Motor	PMSM Motor (Permanent Magnet Synchronous Motor)	Universal Motor	Stepper Motor
				
<ul style="list-style-type: none"> • Computer hard drives • Consumer electronics • HVAC • Electric Cars • Industrial Engineering 	<ul style="list-style-type: none"> • Industrial Applications • HVAC • Electric Cars 	<ul style="list-style-type: none"> • Fans, Blowers • DC Generators • Centrifugal Pumps • Paper Mills 	<ul style="list-style-type: none"> • ‘White goods’ (washing machines, kitchen appliances, ...) • Traction Motors (Railways) • Starter Motors in Cars 	<ul style="list-style-type: none"> • Hard Disk Drives • Robotics • Antennas • Telescopes • Toys
<ul style="list-style-type: none"> • Better speed vs torque • High dynamic response • High efficiency • Long operating life • Noiseless operation • Higher speed ranges 	<ul style="list-style-type: none"> • Simple, robust & mechanically strong • Relative lower cost • Can work in hazardous conditions • High efficiency (85%-95%) 	<ul style="list-style-type: none"> • High performance in both low and high speed operation • Low rotor inertia, easy to control • Higher torque 	<ul style="list-style-type: none"> • Efficiency 70%-75% • Torque vs speed • Speed control 	<ul style="list-style-type: none"> • Low cost • High reliability • High torque at low speed • Simple and rugged • Operates in almost any environment







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Types of Drives

AC Drives	DC Drives	Variable Frequency Drives	Servo Drives
			
<ul style="list-style-type: none"> • Constant speed motors e.g. Process industry • HVAC (fans, pumps, compressors) 	<ul style="list-style-type: none"> • Crane and hoists • Elevators • Spindle drives • Winders • Paper production machines 	<p>Controls speed of AC motors</p> <ul style="list-style-type: none"> • Conveyor systems • Blower speeds • Pump speeds • Machine tool speeds 	<ul style="list-style-type: none"> • Robotics • CNC machines • Solar tracking systems • Antenna positioning • Camera auto focus
<ul style="list-style-type: none"> • Low start-up current allow for smaller components and reduce mechanical shock at start-stop • Lower speed results in lower noise levels 	<ul style="list-style-type: none"> • Adjustable speed • Good speed regulation • Frequent starting, breaking, reversing 	<ul style="list-style-type: none"> • Reducing speed will reduce Amps drawn by motor, provides energy efficiency • Reduces in-rush and mechanical issues associated with starting 	<ul style="list-style-type: none"> • High output power relative to motor size and weight • High torque to inertia ratio • More continuous power and torque for short periods

Segmentation per use case

Automotive	Industrial	Consumer	MilGov/Defence/Aero
			
<ul style="list-style-type: none"> • EV/PHEV Power train 	<ul style="list-style-type: none"> • Power tools • Robotics 	<ul style="list-style-type: none"> • Washing machines • Vacuum cleaners 	<ul style="list-style-type: none"> • Planes • Rovers • Drones
<p>Focus on</p> <ul style="list-style-type: none"> • Efficiency • Weight 	<p>Focus on</p> <ul style="list-style-type: none"> • Low noise and vibration 	<p>Focus on</p> <ul style="list-style-type: none"> • Energy savings / efficiency • Cost 	<p>Focus on</p> <ul style="list-style-type: none"> • Precision motion control • Efficiency (drone fly time)

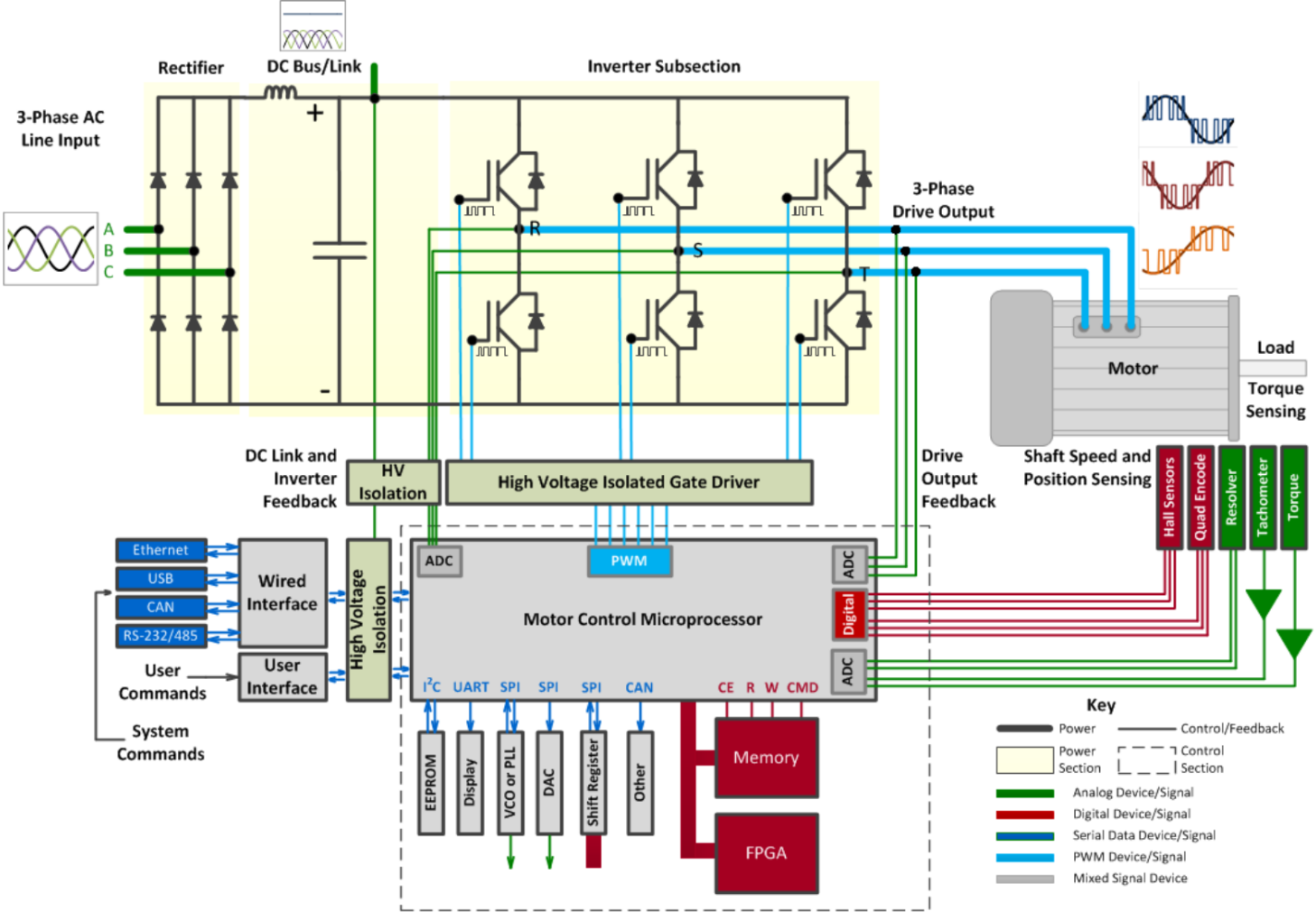
Questions regarding Inverter & Motor Drive Analysis

- How am I testing my Motor Drive Systems and what testing challenges do I have?
- What measurements do I need to make?
- How many channels do I need to monitor/analyze?
- How do I measure the dynamic response of my motor drive circuit?
- What mechanical measurements do I need to make?
- How do I measure magnetic components in my circuit?
- What characteristics of the semiconductor devices used in my circuit do I need to measure?
- How do I characterise the semiconductor devices used in my circuit?
- Do I need to perform Double Pulse measurements? How do I do that?
- How do I measure control loop response of my circuit?
- Which serial buses do I need to decode or measure in the control logic block of my design?
- How do I measure DC power rails in the control logic block of my design?
- Am I using WBG devices in my design? What measurement challenges do I face?
- Do I need to perform Direct Quadrature Zero (DQ0) analysis on my design?
- ...



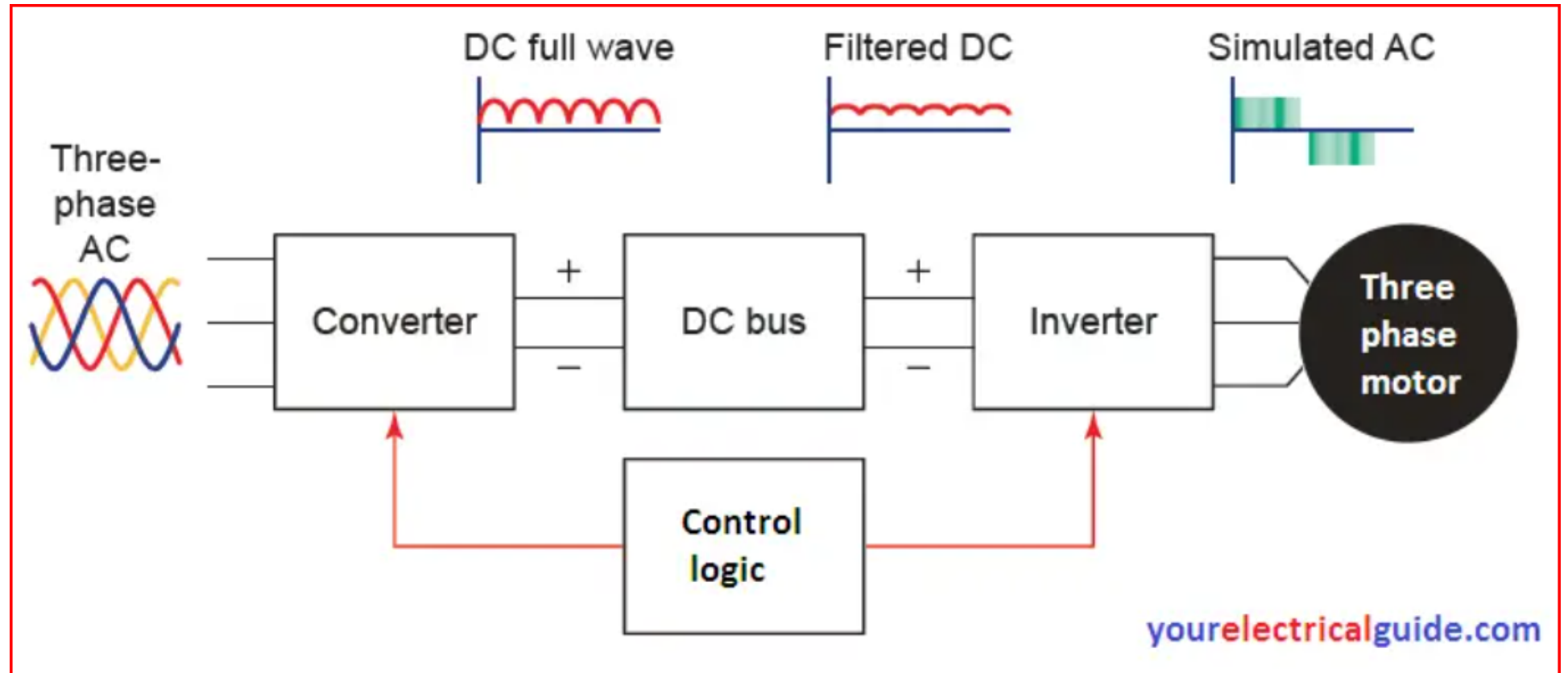
Motor Drive

- Converter
- DC Bus
- Inverter
- Control Logic
- Motor

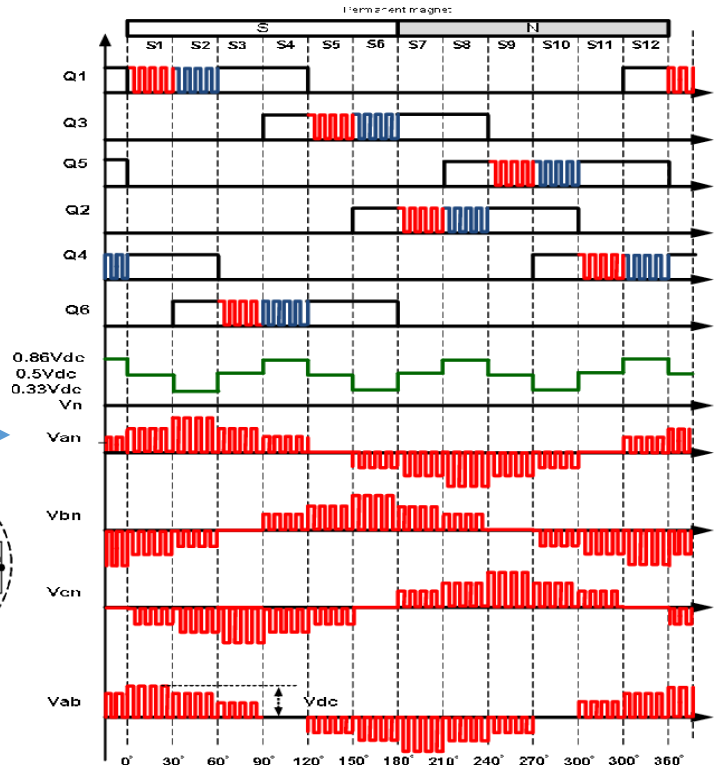
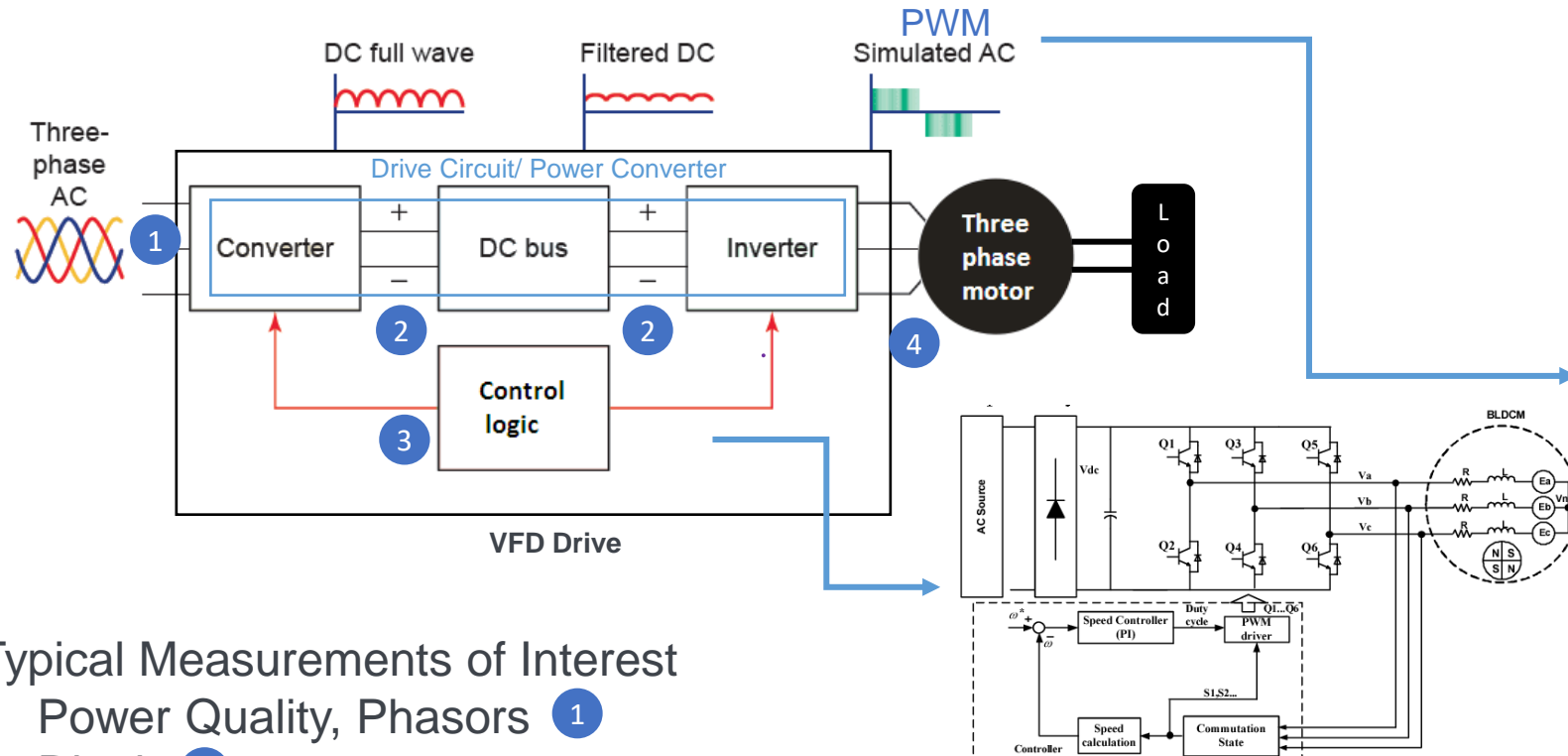


Motor Drive

- Converter
- DC Bus
- Inverter
- Control Logic
- Motor



A typical 3-Phase Motor diagram

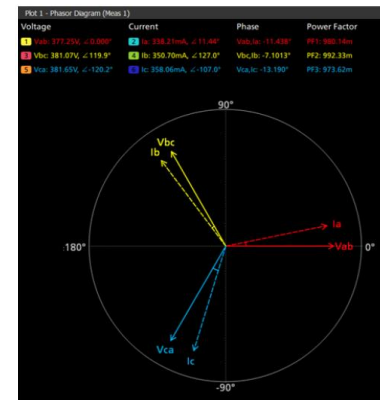
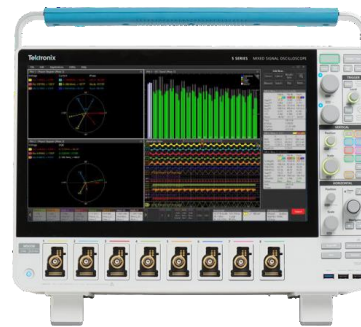
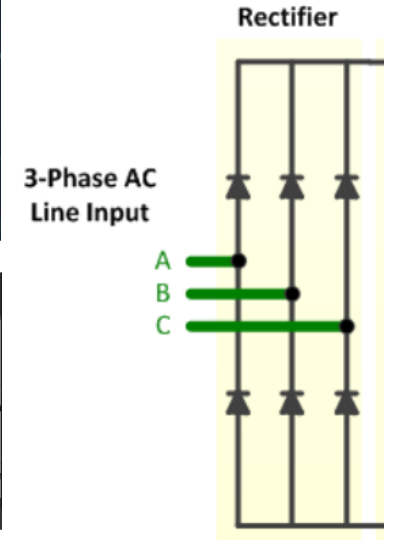
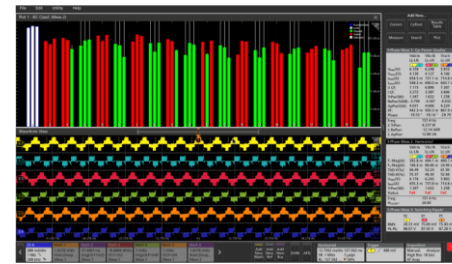
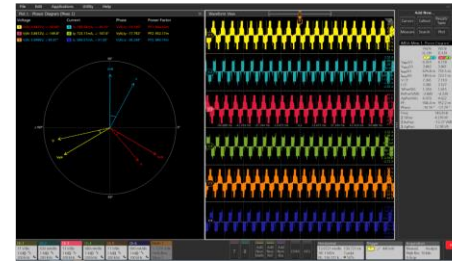


Typical Measurements of Interest

- Power Quality, Phasors ①
- Ripple ②
- Standard 5 Series measurements for control and user interface ③
- Power Quality, Phasors ④
- Efficiency ① ④

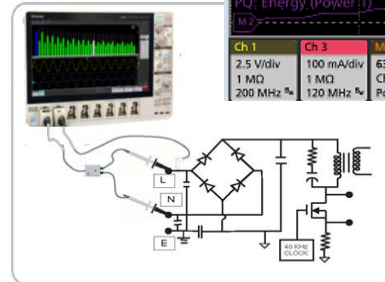
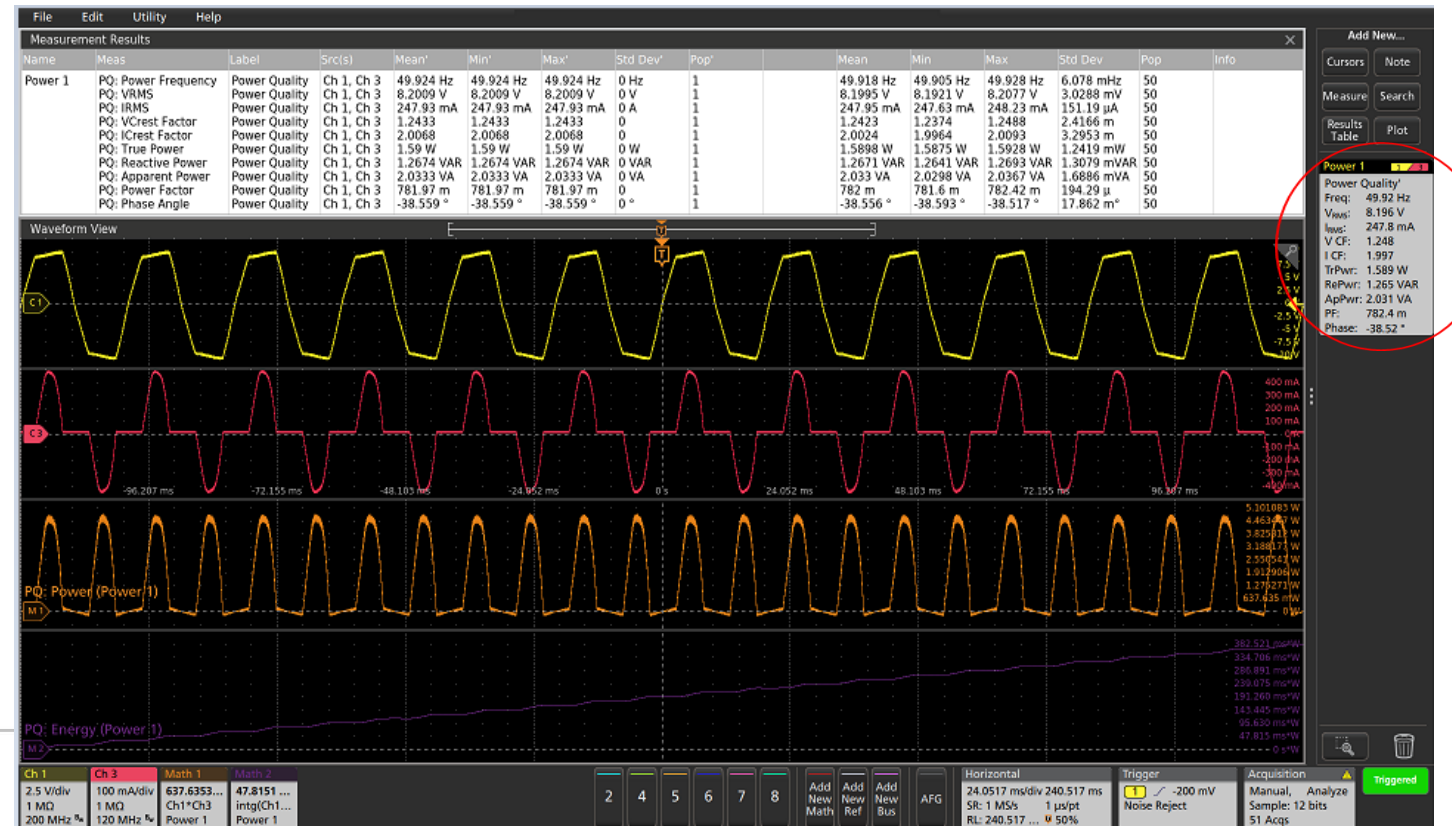
Testing that needs to be done – by building block Converter

- 3-Phase Power Quality
 - Frequency, RMS values, Crest Factors, PWM frequency
- 3-Phase Harmonics analysis
- Phasor Diagram
 - Magnitude and phase angle between voltage and current
 - Power Factor for all voltages and currents



Testing that needs to be done – by building block Converter - Significance of Power Quality

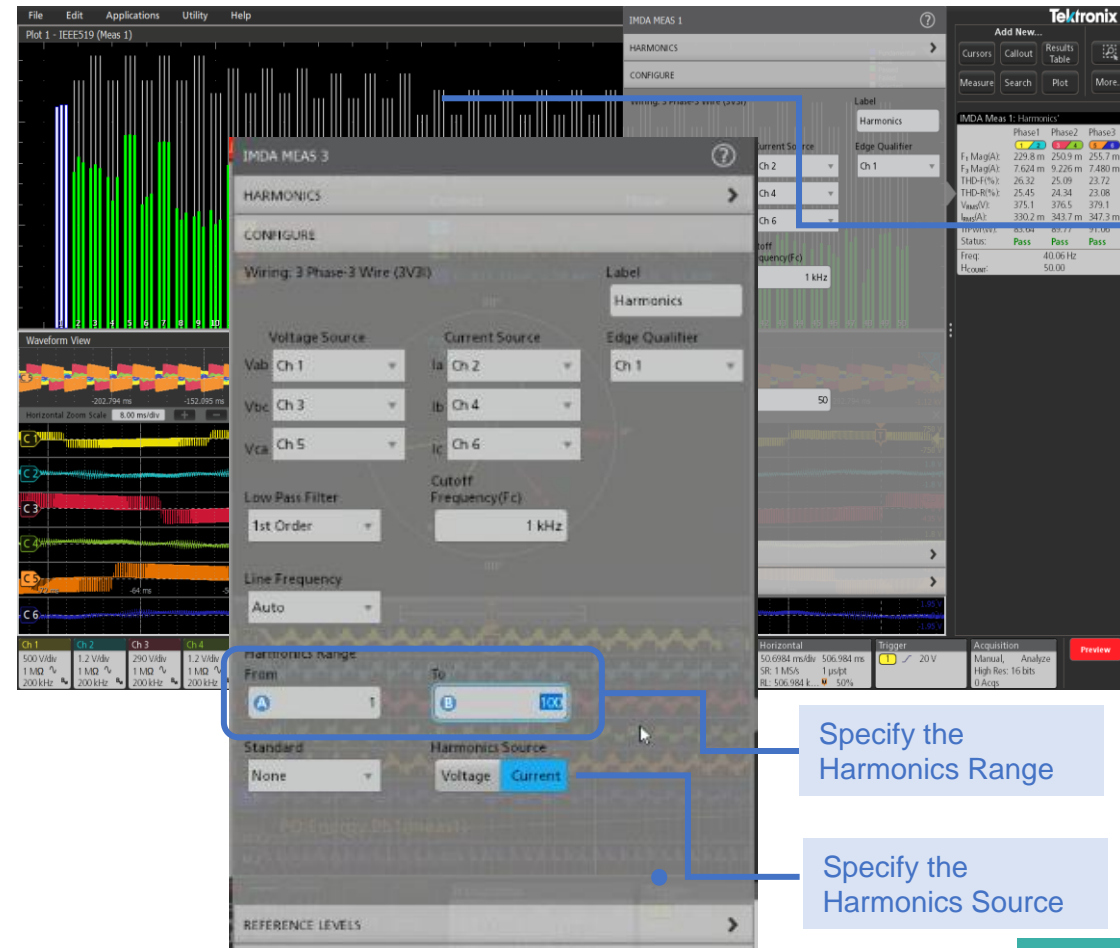
- Reduce losses
 - hence lower energy bills
- Improve Power Factor
 - avoid penalty for low power factor
- Prevent malfunctioning equipment
- Reduce losses in equipment
- Increase power equipment life span



Testing that needs to be done – by building block

Converter - Significance of harmonics analysis

- Harmonics can impact efficiency
 - Can result in heating of coils, misfiring of VFDs, etc
 - Frequent cause of Power Quality Problems
- important sub-measurements such as THD-F, THD-R
- up to 200th order
 - supports range filter for visibility
- Support pass/fail status



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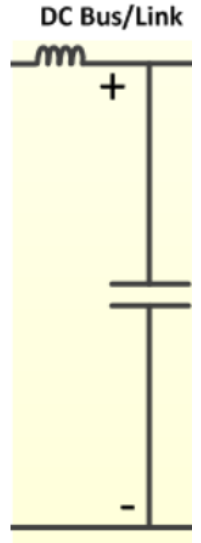
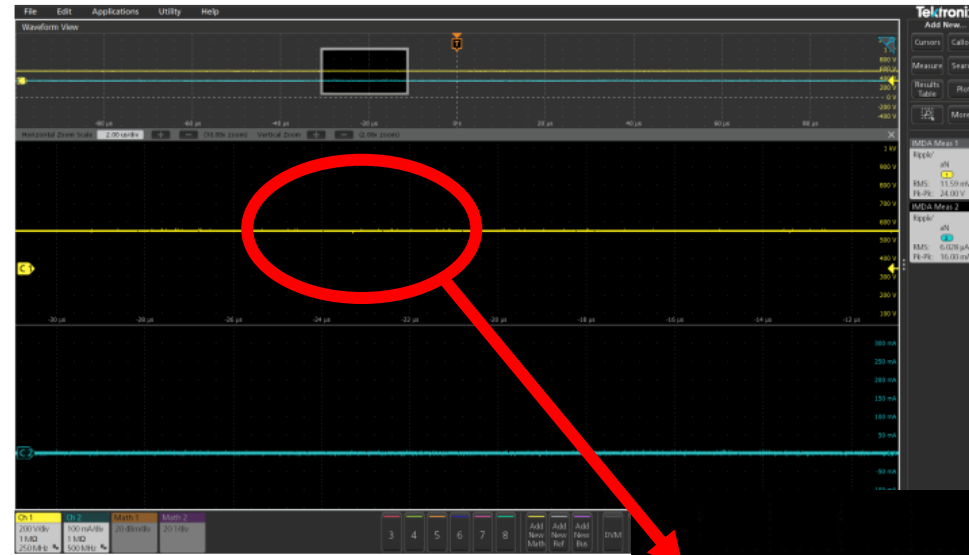
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VFD : Variable Frequency Drive
THD-R : Relative to Total Signal ($0 < \text{THD-R} < 1$)
THD-F : Relative to Fundamental component (IEC61000-2-2)

Testing that needs to be done – by building block

DC Bus

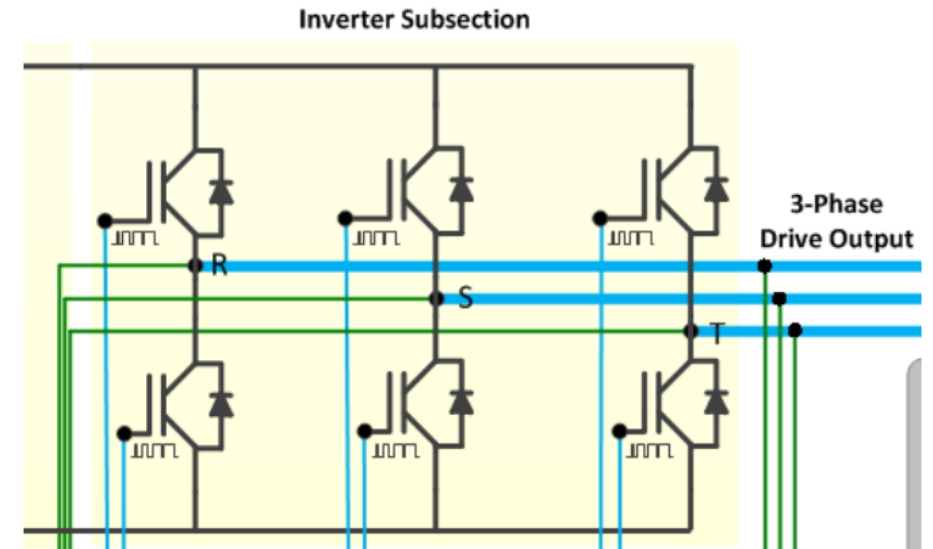
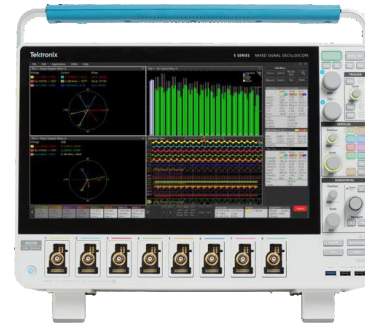
- AC ripple analysis
 - Residual AC voltage on a DC component
 - Can be measured at input or output configuration
- Magnetic analysis



Testing that needs to be done – by building block

Inverter

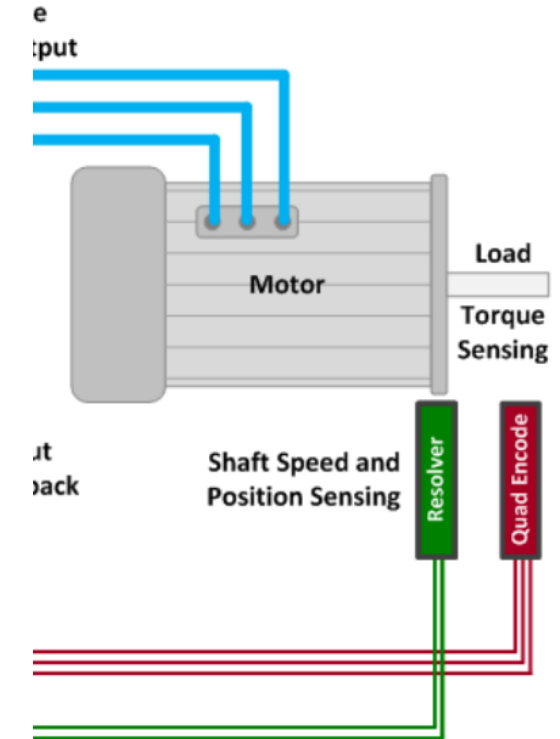
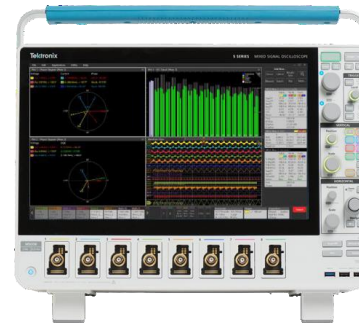
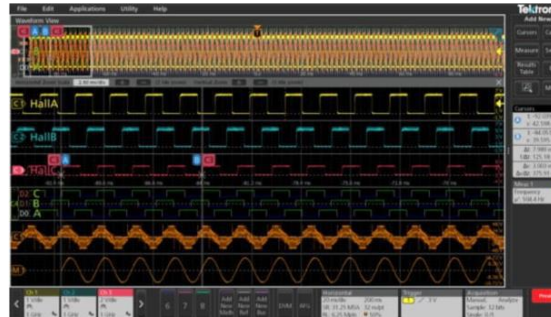
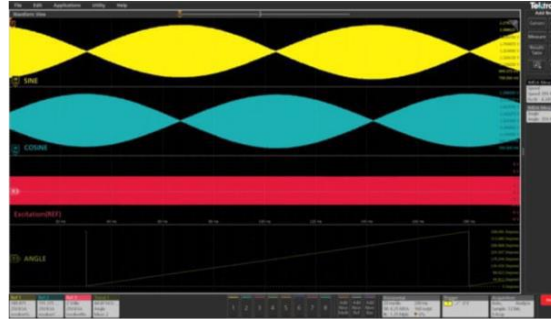
- 3-phase Power Quality
- 3-phase Harmonics analysis
- Semiconductor device switching analysis
- Semiconductor device characterisation
- Safe Operating Area (SOA)
- Amplitude and timing analysis
- Turn on/turn off time analysis
- WBG Double Pulse Testing and switching analysis



Testing that needs to be done – by building block

Motor

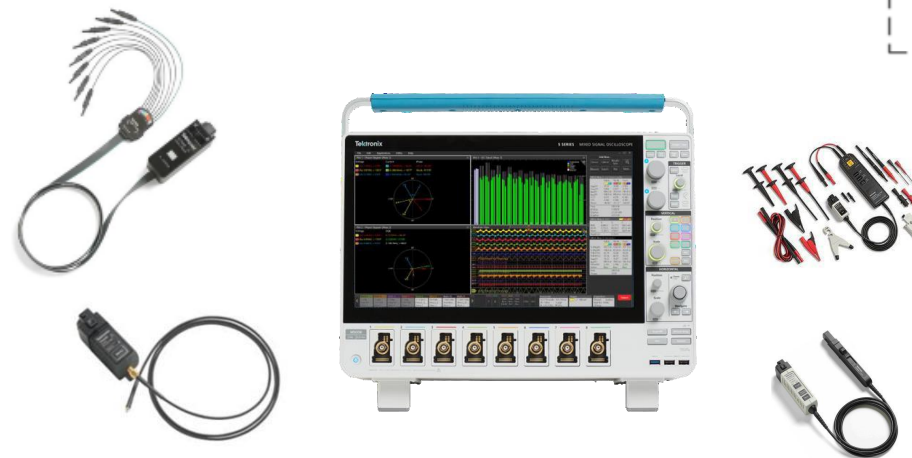
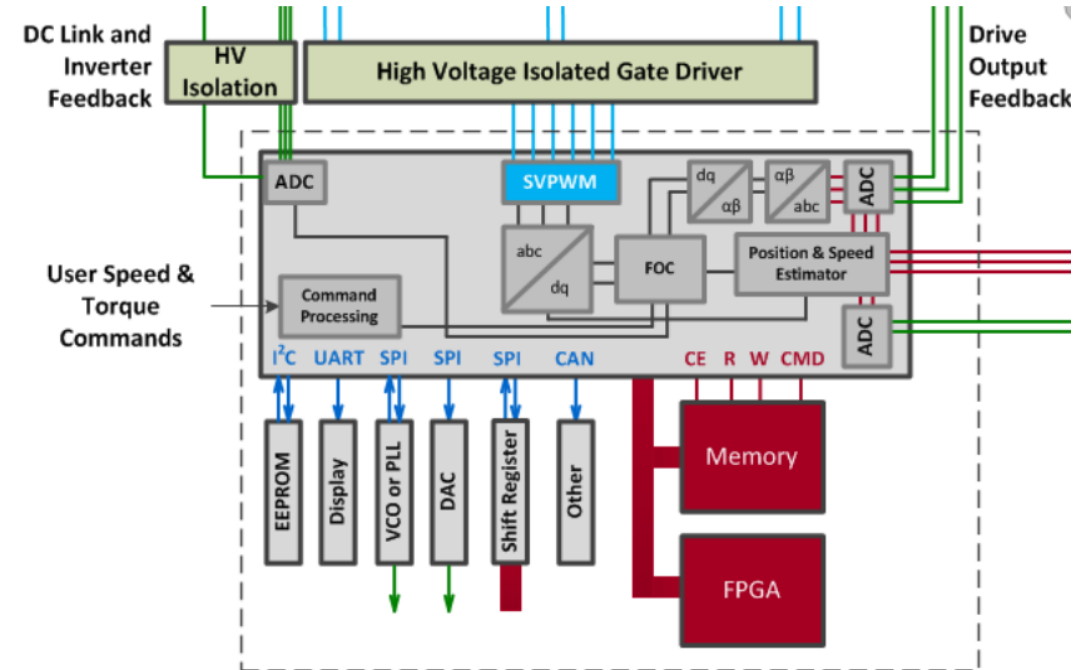
- Mechanical analysis
 - Speed
 - Acceleration
 - Angle
 - Direction
 - Torque
 - Mechanical power
 - System efficiency



Testing that needs to be done – by building block

Control Logic

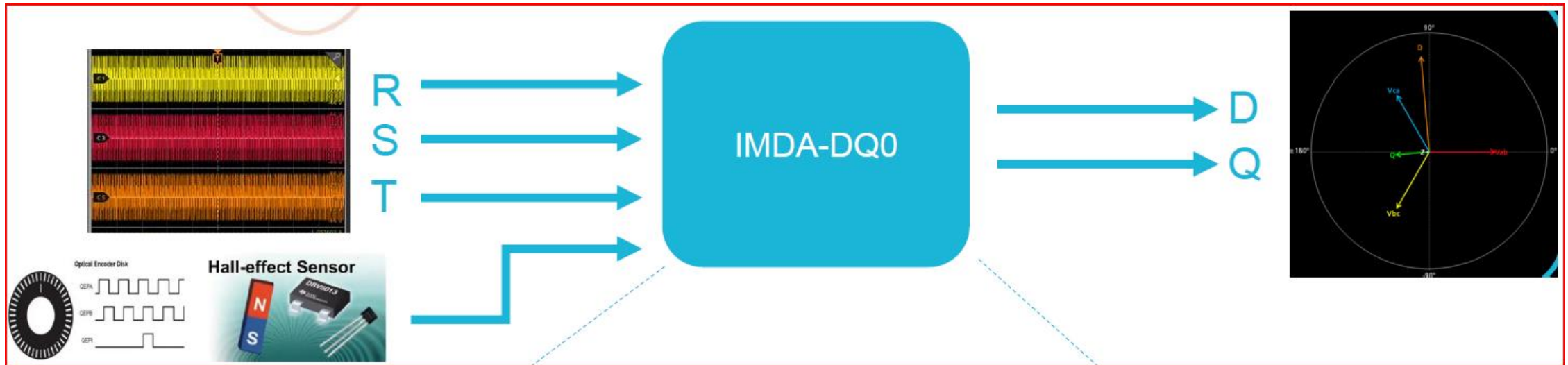
- Direct Quadrature Zero (DQ0) analysis
- Control Loop Analysis
- Serial decoding (CAN, I²C, SPI, ...)
- Mixed Signal analysis
- DC Power Rail analysis



Testing that needs to be done – by building block

Control Logic

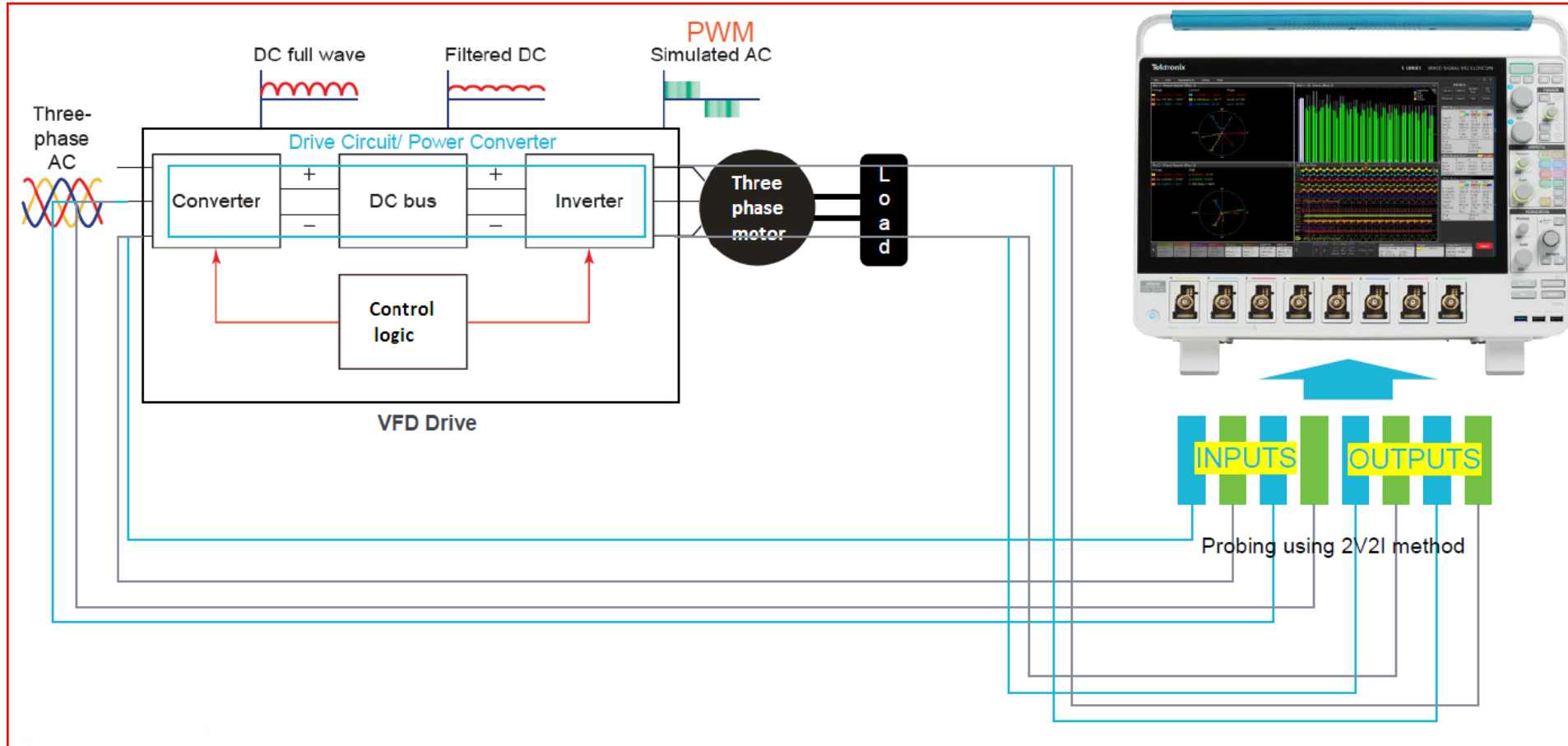
- Direct Quadrature Zero (DQ0) analysis



- Hard to analyze – need three phases to analyze
- Park's Transformation converts raw 3 Phase voltage or current signals into DQ0 components for simplified analysis

Testing that needs to be done – by building block

Efficiency



Thank you!

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Sven De Coster – sdecoster@cnrood.com



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